

Synthèse sur les problèmes de lot sizing et perspectives

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Stéphane DAUZERE-PERES

(avec l'aide de Nabil ABSI et Nadjib BRAHIMI) Département Sciences de la Fabrication et Logistique Centre Microélectronique de Provence – Site Georges Charpak Ecole des Mines de Saint-Etienne

Dauzere-Peres@emse.fr



Outline

- General introduction
- Problem modeling
- Classifications
- Disaggregate and shortest path formulations
- Solving the uncapacitated single-item lot-sizing problem
- · Solving the multi-item lot-sizing problem
- Some extensions of lot-sizing problems
- Modeling and solving multi-level lot-sizing problems
- Integrating lot-sizing decisions with other decisions



General Introduction

- Lot Sizing = Determination of sizes of (production or distribution) lots, i.e. *quantities* of products (to produce or distribute).
- This talk is concerned with "**Dynamic**" lot sizing, i.e. **demands** d_t are varying on a time horizon decomposed in *T* periods.
- The goal is to determine a plan, i.e. the **quantity** X_t at each period *t*, which results in an **inventory level** I_t following the well-known inventory balance equation:

 $I_t = I_{t-1} + X_t - d_t$

Lot Sizing usually means setups,

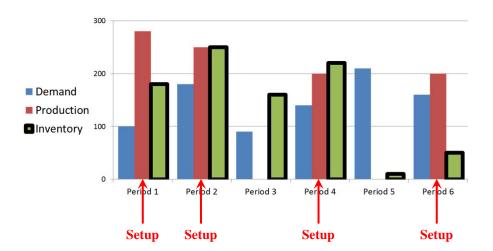
i.e. setup variable $Y_t = 1$ if $X_t > 0$ and, $Y_t = 0$ otherwise.

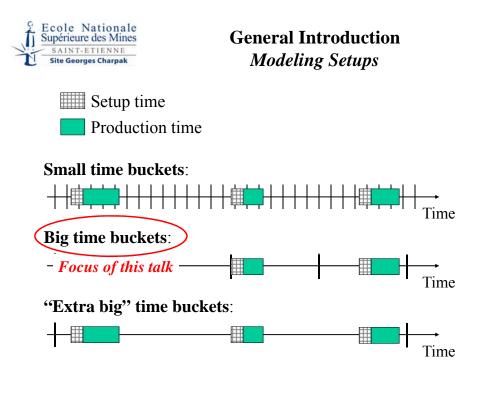
Basic trade-off: *inventory cost vs setup cost*, however production cost vs inventory cost vs setup cost is also possible.



General Introduction

Example of a plan on a single item.

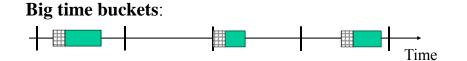






General Introduction Modeling Setups

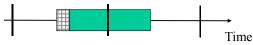
- In big time bucket models, there is one setup for each period in which the product is produced.
- Classical big time bucket models:
 - The Uncapacitated Lot-Sizing Problem (ULSP) (Wagner-Whitin problem)
 - The Capacitated Lot-Sizing Problem (CLSP)





General Introduction Modeling Setups

• In multi-item production, a setup can sometimes be saved by letting the same product produced last in a given period to be produced first in the next period (production **carryovers**):



- Most big time bucket models do not take into account carryovers and, in such cases, small time bucket models may be better suited.
- However, Aras and Swanson [1982] proposed a modification so that production carryovers can also be handled by big time bucket models.



General Introduction Modeling Setups

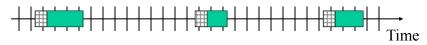
• When time buckets are small, there is only one setup even if a production lot lasts for several periods

 \rightarrow Means of considering scheduling decisions in lot-sizing models

• Some small time bucket models:

- The Discrete Lot-sizing and Scheduling Problem (DLSP), \rightarrow See presentation of C. Gicquel,
- The Continuous Setup Lot-sizing Problem (CSLP),
- The Proportional Lot-sizing and Scheduling Problem (PLSP),
- The General Lot-sizing and Scheduling Problem (GLSP).

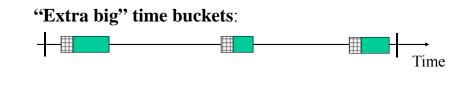
Small time buckets:





General Introduction Modeling Setups

- Time buckets are so big that each individual setup is not important for the total production capacity; there will normally be several setups for each product in the period.
- Setups are therefore not considered at all ("**aggregate production planning**"), and a pure LP model can be used.
- "Average setup time" is either deducted from the total capacity, or production time per unit is increased in order to compensate for the setup time.





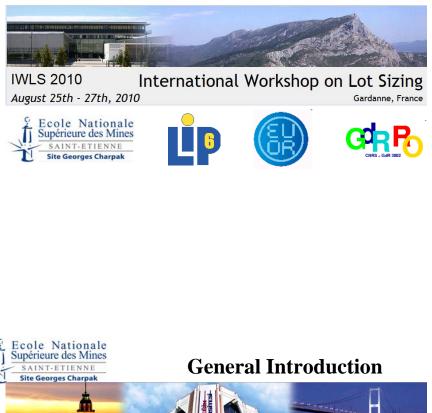
General Introduction

- Lot-Sizing problems are useful in production and distribution, where many practical problems can be found.
- The study of lot-sizing problems has been driven by the development of APS (Advanced Planning Systems).



General Introduction

Renewal from the mid-2000's, illustrated by the success of the International Workshop on Lot Sizing (IWLS) started in Gardanne in 2010.







Problem modeling

Uncapacitated Lot-Sizing Problem (USLP)

• Decision variables:

- $Y_t = 1$ if production (setup) in period $t_t = 0$ otherwise
- X_t = Production quantity in period t
- I_t = Inventory at the end of period t

• Parameters:

- d_t = Demand in period t
- v_t = Variable production cost per unit in period t
- s_t = Setup cost in period t
- c_t = Inventory holding cost per unit on stock at the end of period t



Problem modeling Uncapacitated Lot-Sizing Problem (USLP)

$$\operatorname{Min} \quad \sum_{t=1}^{T} \left(s_t Y_t + v_t X_t + c_t I_t \right)$$

subject to :

$$\begin{aligned} X_t + I_{t-1} - I_t &= d_t & \forall t \\ X_t &\leq M_t Y_t & \forall t \\ X_t, I_t &\geq 0 & \forall t \\ Y_t &= \{0, 1\} & \forall t \end{aligned}$$

Where M_t is an upper bound of X_t , e.g. $M_t = d_t + \ldots + d_T$.



Problem modeling Uncapacitated Lot-Sizing Problem (USLP)

Analysis of the Linear Relaxation, i.e. when $Y \ge 0$.

What happens to Y_t in an optimal solution?

- \rightarrow Y_t will be equal to X_t / M_t (as long as setup cost s_t > 0),
- \rightarrow If M_t is much larger than X_t , then Y_t will be close to zero,
- → Optimal value of LP relaxation will be much lower than optimal value of original problem.
- \rightarrow Efficiency of standard solvers depend on choice of M_t .
- \rightarrow Various valid inequalities have been proposed.



Problem modeling Uncapacitated Lot-Sizing Problem (USLP)

Valid inequality (*l*, *S*). (Barany, Van Roy and Wolsey, 1984) By definition, if there is a production in period *t* (i.e. $X_t > 0$ and $Y_t = 1$), then d_t is produced in *t*.

 \rightarrow The following inequality is valid: $X_t \leq d_t Y_t + I_t$.

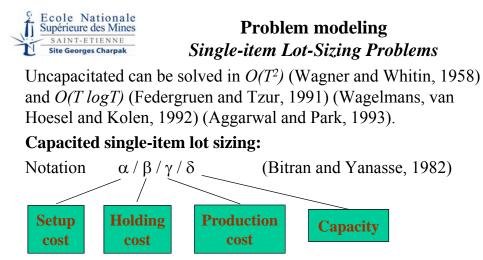
This inequality can be generalized to two periods:

 $X_t + X_{t+1} \le (d_t + d_{t+1})Y_t + d_{t+1}Y_{t+1} + I_{t+1}$

and to any number of periods.

(*l*, *S*) inequalities (exponential number) can be used to fully describe the convex hull of the USLP.

$$\sum_{l \in S} X_l \le \sum_{l \in S} \left(\sum_{k=l}^{t} d_k \right) Y_l + I_t \qquad \forall t , \forall S \subseteq \{1, \dots, t\}$$



 α , β , γ , δ = Z (Zero), C (Constant), NI (Non Increasing), ND (Non Decreasing), G (General)



Problem modeling Single-item Lot-Sizing Problems

Capacited single-item lot sizing:

The general case is NP-hard.

Polynomial cases:

Problem	Complexity	References
NI/G/NI/ND	$O(T^4)$ $O(T^2)$	Bitran and Yanasse (1982) Chung and Lin (1988)
NI/G/NI/C	$O(T^3)$	Bitran and Yanasse (1982)
C/Z/C/G	$O(T\log T)$	Bitran and Yanasse (1982)
ND/Z/ND/NI	O(T)	Bitran and Yanasse (1982)
G/G/G/C	$O(T^4)$ $O(T^3)$	Florian and Klein (1971) Van Hoesel and Wagelmans (1996)



Problem modeling

Multi-item Lot-Sizing Problem (CLSP)

• Decision variables:

- $Y_{it} = 1$ if production (setup) of item *i* in period *t*, = 0 otherwise
- X_{it} = Production quantity of item *i* in period *t*
- I_{it} = Inventory of item *i* at the end of period *t*

• Parameters:

 d_{it} = Demand for item *i* in period *t*

- v_{it} = Variable production cost per unit of item *i* in period *t*
- s_{it} = Setup cost for item *i* in period *t*
- c_{it} = Inventory holding cost per unit of item *i* on stock at the end of period *t*
- p_{it} = Production time per unit of item *i* in period *t*
- h_t = Available time for production in period t



Problem modeling Multi-item Lot-Sizing Problem (CLSP)

Min
$$\sum_{i=1}^{N} \sum_{t=1}^{T} (s_{it}Y_{it} + v_{it}X_{it} + c_{it}I_{it})$$

subject to :

$$\begin{aligned} X_{it} + I_{it-1} - I_{it} &= d_{it} & \forall i, \forall t \\ \sum_{i=1}^{N} p_{it} X_{it} &\leq h_t & \forall t \\ X_{it} &\leq M_{it} Y_{it} & \forall i, \forall t \\ X_{it}, I_{it} &\geq 0 & \forall i, \forall t \\ Y_{it} &\in \{0,1\} & \forall i, \forall t \end{aligned}$$

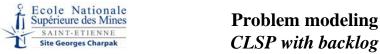
CLSP is NP hard in the strong sense (Chen and Thizy, 1990).

É Ecole Nationale Supérieure des Mines	Problem modeling
SAINT-ETIENNE Site Georges Charpak	U
Site Georges Charpak	CLSP with setup times

New parameter: τ_{it} = Fixed setup time of item *i* in period *t*

$$\begin{array}{ll} \text{Min} & \sum_{i=1}^{N} \sum_{t=1}^{T} \left(s_{it}Y_{it} + v_{it}X_{it} + c_{it}I_{it} \right) \\ & X_{it} + I_{it-1} - I_{it} = d_{it} & \forall i, \forall t \\ & \sum_{i=1}^{N} p_{it}X_{it} + \sum_{i=1}^{N} \tau_{it}Y_{it} \leq h_{t} & \forall t \\ & X_{it} \leq M_{it}Y_{it} & \forall i, \forall t \\ & X_{it}, I_{it} \geq 0 & \forall i, \forall t \\ & Y_{it} \in \{0,1\} & \forall i, \forall t \end{array}$$

With setup times, checking that a feasible solution exists is already NP-Complete (Trigeiro, Thomas and McClain, 1989).



New variable: B_{it} = Backlog of item *i* at the end of period *t* New parameter: b_{it} = Variable cost per unit of *i* backordered in *t*

$$\begin{array}{ll}
\text{Min} & \sum_{i=1}^{N} \sum_{t=1}^{T} \left(s_{it} Y_{it} + v_{it} X_{it} + c_{it} I_{it} + b_{it} B_{it} \right) \\
& X_{it} + (I_{it-1} - B_{it-1}) - (I_{it} - B_{it}) = d_{it} \quad \forall i, \forall t \\
& \sum_{i=1}^{N} p_{it} X_{it} + \sum_{i=1}^{N} \tau_{it} Y_{it} \leq h_{t} \quad \forall t \\
& X_{it} \leq M_{it} Y_{it} \quad \forall i, \forall t \\
& X_{it}, I_{it}, B_{it} \geq 0 \quad \forall i, \forall t \\
& Y_{it} \in \{0, 1\} \quad \forall i, \forall t
\end{array}$$

Single-item case solved in $O(T^2)$ with an extension of Wagner-Whitin algorithm (Zangwill, 1969).



Problem modeling CLSP with lost sales

New variable: L_{it} = Lost sale of item *i* at the end of period *t* **New parameter:** l_{it} = Variable cost per unit of *i* lost in *t*

$$\begin{array}{ll} \text{Min} & \sum_{i=1}^{N} \sum_{t=1}^{I} \left(s_{it} Y_{it} + v_{it} X_{it} + c_{it} I_{it} + l_{it} L_{it} \right) \\ & X_{it} + I_{it-1} - (I_{it} - L_{it}) = d_{it} & \forall i, \forall t \\ & \sum_{i=1}^{N} p_{it} X_{it} + \sum_{i=1}^{N} \tau_{it} Y_{it} \leq h_{t} & \forall t \\ & X_{it} \leq M_{it} Y_{it} & \forall i, \forall t \\ & X_{it}, I_{it}, L_{it} \geq 0 & \forall i, \forall t \\ & Y_{it} \in \{0,1\} & \forall i, \forall t \end{array}$$

Single-item case solved in $O(T^2)$ (Aksen, Altinkemer and Chand, 2003).

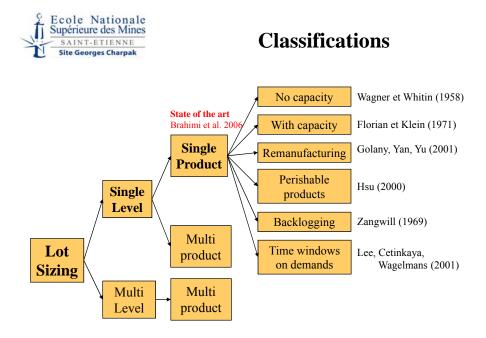


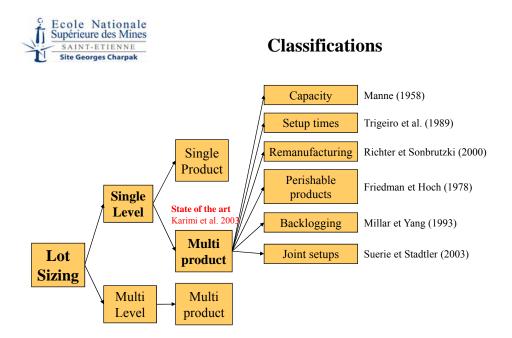
Problem modeling CLSP with lost sales

New variable: L_{it} = Lost sale of item *i* at the end of period *t* **New parameter:** l_{it} = Variable cost per unit of *i* lost in *t*

$$\begin{array}{ll} \text{Min} & \sum_{i=1}^{N} \sum_{t=1}^{T} \left(s_{it} Y_{it} + v_{it} X_{it} + c_{it} I_{it} + l_{it} L_{it} \right) \\ & X_{it} + I_{it-1} - (I_{it} - L_{it}) = d_{it} & \forall i, \forall t \\ & \sum_{i=1}^{N} p_{it} X_{it} + \sum_{i=1}^{N} \tau_{it} Y_{it} \leq h_{t} & \forall t \\ & X_{it} \leq M_{it} Y_{it} & \forall i, \forall t \\ & X_{it}, I_{it}, L_{it} \geq 0 & \forall i, \forall t \\ & Y_{it} \in \{0,1\} & \forall i, \forall t \end{array}$$

Lagrangian based metaheuristics proposed for the multi-item case (Absi, Detienne and D.-P., 2013).







Tighter formulations

Multiple formulations were proposed for the single-item and multi-item problems **to improve on the linear relaxation of the aggregate formulation**, and get better solutions with a standard solver.



Disaggregate formulation

orges Charpak Uncapacitated Lot-Sizing Problem (ULSP)

Also called facility location model (Krarup and Bilde, 1977).

- New variable: Z_{tk} = quantity produced in period *t* to cover demand in period *k*.
- New parameter: cd_{tk} = variable production cost plus inventory cost for producing one unit in period t and storing it until period k, i.e.

$$cd_{tk} = v_t + c_t + c_{t+1} + c_{t+2} + \dots + c_{k-2} + c_{k-1} = v_t + \sum_{u=t}^{k-1} c_u$$



Disaggregate formulation Uncapacitated Lot-Sizing Problem (ULSP)

$$\begin{aligned} \text{Min} \qquad \sum_{t=1}^{T} s_t Y_t + \sum_{t=1}^{T} \sum_{k=t}^{T} c d_{tk} Z_{tk} \\ \sum_{t=1}^{k} Z_{tk} = d_k \qquad \forall k \\ Z_{tk} \leq d_k Y_t \qquad \forall t, \forall k \geq t \\ Z_{tk} \geq 0 \qquad \forall t, \forall k \geq t \\ Y_t = \{0, 1\} \qquad \forall t \end{aligned}$$



Disaggregate formulation Capacited Lot-Sizing Problem (CLSP)

- New variable: Z_{iik} = quantity of item *i* produced in period *t* to cover demand in period *k*.
- New parameter: cd_{itk} = variable production cost plus inventory cost for producing one unit of item *i* in period *t* and storing it until period *k*, i.e.

$$cd_{itk} = v_{it} + c_{it} + c_{it+1} + c_{it+2} + \dots + c_{ik-2} + c_{ik-1} = v_{it} + \sum_{u=t}^{k-1} c_{iu}$$

Disaggregate formulation *Capacited Lot-Sizing Problem (CLSP)*

$$\sum_{i=1}^{N} \sum_{t=1}^{T} s_{it} Y_{it} + \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{k=t}^{T} cd_{itk} Z_{itk}$$

$$\sum_{t=1}^{k} Z_{itk} = d_{ik} \qquad \forall i, \forall k$$

$$\sum_{i=1}^{N} \sum_{k=t}^{T} p_{it} Z_{itk} + \sum_{i=1}^{N} \tau_{it} Y_{it} \le h_t \qquad \forall t$$

$$Z_{itk} \le d_{it} Y_{it} \qquad \forall i, \forall t, \forall k \ge t$$

$$Z_{itk} \ge 0 \qquad \forall i, \forall t, \forall k \ge t$$

$$Y_{it} \in \{0,1\} \qquad \forall i, \forall t$$



Shortest Path formulation *Capacited Lot-Sizing Problem (CLSP)*

(Eppen and Martin, 1987)

- New variable: ZZ_{itk} = fraction of total demand of item *i* for periods *t* through *k* that is produced in period *t* (\in [0,1]).
- New parameter: cc_{itk} = variable production cost plus inventory cost for producing in period *t* and storing the demands from periods *t* to *k* of item *i*, i.e.

$$cc_{itk} = \sum_{l=t}^{k} v_{it} d_{il} + c_{it} \sum_{l=t+1}^{k} d_{il} + c_{it+1} \sum_{l=t+2}^{k} d_{il} + \dots + c_{ik-1} d_{ik}$$
$$cc_{itk} = \sum_{l=t}^{k} v_{it} d_{il} + \sum_{u=t}^{k-1} c_{iu} \sum_{l=u+1}^{k} d_{il}$$

Shortest Path formulation Capacited Lot-Sizing Problem (CLSP)

Min $\sum_{i=1}^{N} \sum_{i=1}^{T} s_{it} Y_{it} + \sum_{i=1}^{N} \sum_{i=1}^{T} \sum_{i=1}^{T} c c_{itk} Z Z_{itk}$

$$\begin{array}{l} \overline{i=1} \ \overline{t=1} & \overline{t=1} & \overline{t=1} \ \overline{t=$$



Solving the single-item case Wagner-Whitin algorithm

- In the uncapacitated case, the **Zero Inventory Order (ZIO)** property is satisfied, i.e. plans where " $I_{t-1}X_t = 0 \forall t$ " are dominant
- → Order quantities cover an integer number of periods in dominant plans,
- \rightarrow There is an optimal solution which is a dominant plan,
- \rightarrow Wagner Whitin algorithm uses ZIO property,
- → ZIO property often checked when analyzing a new lot-sizing problem.



Solving the single-item case Wagner-Whitin algorithm

Example.

setup cost $\forall t$ $s_t = 15$ $c_{t} = 1$ inventory cost $\forall t$ demand $d_t = (4, 8, 6, 7)$ The dominant plans are: (4, 8, 6, 7) (4, 8, 13, 0) (4, 14, 0, 7) (4,21,0,0) (12, 0, 6, 7) (12, 0, 13, 0)(18, 0, 0, 7)(25, 0, 0, 0)



Solving the single-item case Wagner-Whitin algorithm

In general, there will be $2^{(T-1)}$ dominant plans.

By using dynamic programming, the Wagner-Whitin algorithm further reduces the complexity of the search to T(T+1)/2, i.e. $O(T^2)$ (Wagner and Whitin, 1958).



Solving the single-item case Wagner-Whitin algorithm

Example.

setup cost	$s_t = 15$	$\forall t$
inventory cost	$c_t = 1$	$\forall t$
demand	$d_t = (4, 8, 6,$	7)

Optimal solution.

$X_1 = 12$	$X_2 = 0$	$X_3 = 13$	$X_4 = 0$
$I_1 = 8$	$I_2 = 0$	$I_3 = 7$	$I_4 = 0$
$Y_1 = 1$	$Y_2 = 0$	$Y_3 = 1$	$Y_4 = 0$
Setup costs:			30
Inventory costs:		15	
Total costs:			45



Solving the single-item case Wagner-Whitin algorithm

In general, there will be $2^{(T-1)}$ dominant plans.

- By using dynamic programming, the Wagner-Whitin algorithm further reduces the complexity of the search to T(T+1)/2, i.e. $O(T^2)$ (Wagner and Whitin, 1958).
- More recently, the complexity has been reduced to $O(T \log(T))$ (Federgruen and Tzur, 1991), (Wagelmans Van Hoesel and Kolen, 1992), (Aggarwal and Park, 1993).



Solving the single-item case *Heuristics*

Heuristics for single-item problems can be useful to solve more complex problems and to develop heuristics for multi-item problems:

- *Part-Period Balancing* Aims at balancing total ordering cost and total holding cost
- *Silver and Meal heuristic* Aims at minimizing the cost per period
- Least Unit Cost Aims at minimizing the total cost per unit of product



Solving the multi-item case Lagrangian relaxation

Applying Lagrangian relaxation by relaxing coupling capacity constraints (Trigeiro, Thomas and McClain, 1989).

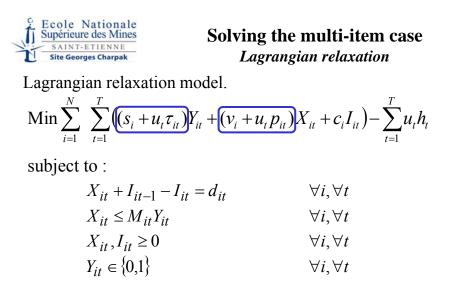
Lagrangian relaxation model.

$$\operatorname{Min}\sum_{i=1}^{N} \sum_{t=1}^{T} \left((s_{i} + u_{t}\tau_{it})Y_{it} + (v_{i} + u_{t}p_{it})X_{it} + c_{i}I_{it} \right) - \sum_{t=1}^{T} u_{t}h_{t}$$

subject to :

$X_{it} + I_{it-1} - I_{it} = d_{it}$	$\forall i, \forall t$
$X_{it} \le M_{it} Y_{it}$	$\forall i, \forall t$
$X_{it}, I_{it} \ge 0$	$\forall i, \forall t$
$Y_{it} \in \{0,1\}$	$\forall i, \forall t$

 \rightarrow Uncapacitated single-item problems (Wagner Whitin problem) can be solved separately in $O(T \log T)$.



Note that Lagrangian production and setup costs are period dependent.



Solving the multi-item case *Lagrangian relaxation heuristic*

- **1. Solve Lagrangian relaxation model** to determine optimal values of variables X_{it} and Y_{it} .
- **2.** Use solution to **compute Lagrangian lower bound** of optimal solution.
- **3.** Use values of variables obtained in Step 1 to **determine a feasible solution** of original problem (*smoothing heuristic*). Update upper bound (best feasible solution).
- **4. Update Lagrange multipliers** (subgradient), so that relaxed capacity constraints not satisfied have more chances to be satisfied at next iteration.

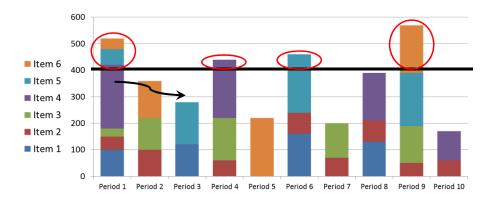
Go to Step 1 if none of the stopping criteria is satisfied (duality gap small enough, step size, number of iterations, ...).

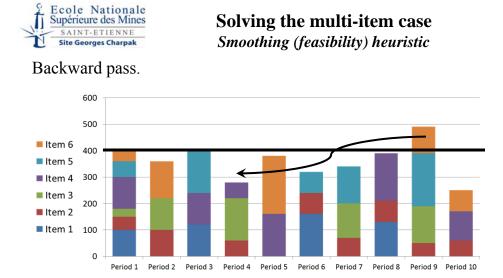


Solving the multi-item case *Smoothing (feasibility) heuristic*

The goal is to ensure feasibility of the plan through forward and backward passes.

Forward pass.

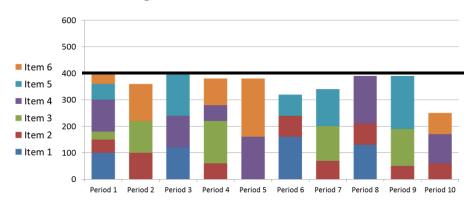






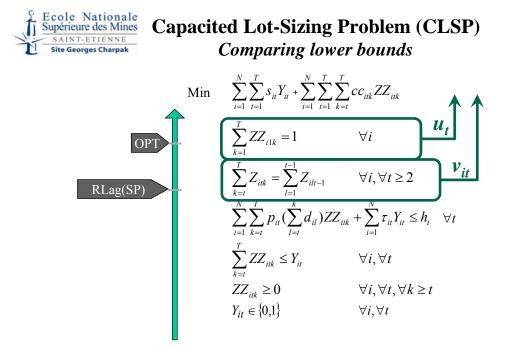
Solving the multi-item case Smoothing (feasibility) heuristic

Leads to a feasible plan.



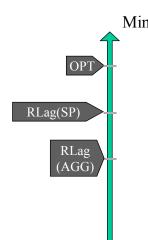
Feasibility is not guaranteed (in particular with setup times).

→ Smoothing heuristics can be applied after any heuristic building initial unfeasible solutions.





Capacited Lot-Sizing Problem (CLSP) Comparing lower bounds



$$\sum_{i=1}^{N} \sum_{t=1}^{T} (s_{it}Y_{it} + v_{it}X_{it} + c_{it}I_{it})$$

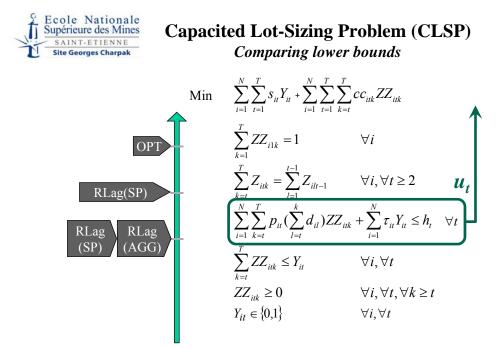
$$X_{it} + I_{it-1} - I_{it} = d_{it} \quad \forall i, \forall t$$

$$\sum_{i=1}^{N} p_{it}X_{it} \leq c_{t} \quad \forall t$$

$$X_{it} \leq M_{it}Y_{it} \quad \forall i, \forall t$$

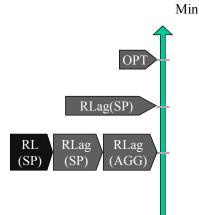
$$X_{it}, I_{it} \geq 0 \quad \forall i, \forall t$$

$$Y_{it} \in \{0,1\} \quad \forall i, \forall t$$

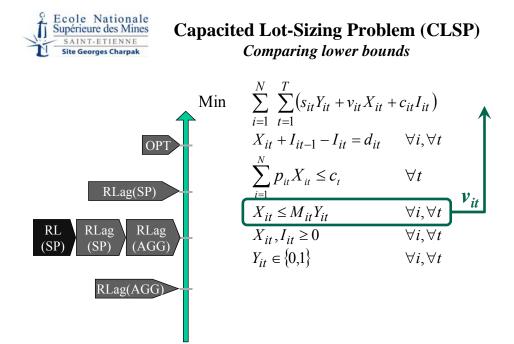




Capacited Lot-Sizing Problem (CLSP) Comparing lower bounds

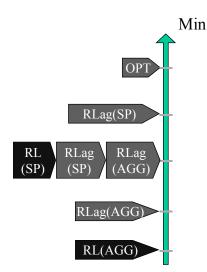


$$\begin{split} \sum_{i=1}^{N} \sum_{t=1}^{T} s_{it} Y_{it} + \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{k=t}^{T} c c_{itk} Z Z_{itk} \\ \sum_{k=1}^{T} Z Z_{i1k} = 1 \qquad \forall i \\ \sum_{k=t}^{T} Z_{itk} = \sum_{l=1}^{t-1} Z_{ilt-1} \qquad \forall i, \forall t \ge 2 \\ \sum_{i=1}^{N} \sum_{k=t}^{T} p_{it} (\sum_{l=t}^{k} d_{il}) Z Z_{itk} + \sum_{i=1}^{N} \tau_{it} Y_{it} \le h_t \quad \forall t \\ \sum_{k=t}^{T} Z Z_{itk} \le Y_{it} \qquad \forall i, \forall t \\ Z Z_{itk} \ge 0 \qquad \forall i, \forall t, \forall k \ge t \\ Y_{it} \in \{0,1\} \qquad \forall i, \forall t \end{split}$$





Capacited Lot-Sizing Problem (CLSP) Comparing lower bounds



$$\sum_{i=1}^{N} \sum_{t=1}^{T} (s_{it}Y_{it} + v_{it}X_{it} + c_{it}I_{it})$$

$$X_{it} + I_{it-1} - I_{it} = d_{it} \quad \forall i, \forall t$$

$$\sum_{i=1}^{N} p_{it}X_{it} \leq c_{t} \quad \forall t$$

$$X_{it} \leq M_{it}Y_{it} \quad \forall i, \forall t$$

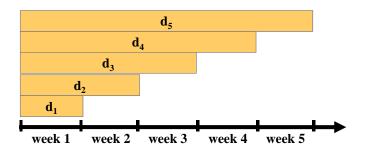
$$X_{it}, I_{it} \geq 0 \quad \forall i, \forall t$$

$$Y_{it} \in \{0,1\} \quad \forall i, \forall t$$



Lot Sizing with Time Windows

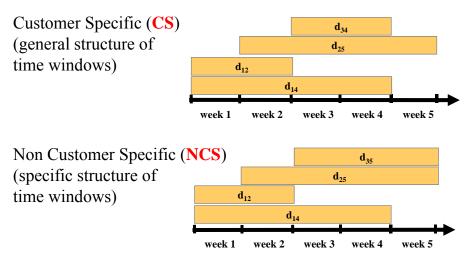
In classical lot-sizing problems without time windows, all demands can be processed as early as the first period.





Lot Sizing with Time Windows

In lot-sizing problems with time windows, each demand d_{st} must be processed within the time window [s,t].





Lot Sizing with Time Windows

Complexity for Customer Specific (CS) single-item problem

- Solved using dynamic programming in exponential time in (D.-P., Brahimi, Najid and Nordli, 2002).
- Solved in $O(T^5)$ in (Huang, 2007)

Complexity for Non Customer Specific (NCS) single-item problem

- Exponential time algorithm for CS problem runs in *O*(*T*⁴) for NCS problem (D.-P., Brahimi, Najid and Nordli, 2002).
- Improved to $O(T^2)$ in (Wolsey, 2006).
- Generalization to early productions, backlogs and lost sales solved in $O(T^2)$ in (Absi, Kedad-Sidhoum and D.-P., 2011).

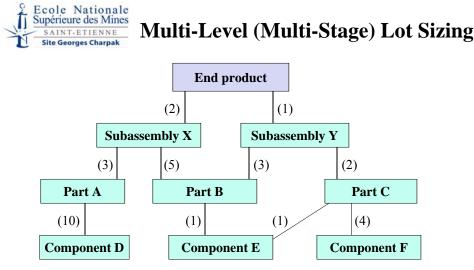
Lagrangian relaxation heuristics proposed in (Brahimi, D.-P. and Najid, 2006) **for CS and NCS multi-item problems.**



Green Lot Sizing

Lot Sizing with carbon emissions

- Recent research on lot sizing is concerned with considering new environmental constraints.
- A global carbon emission constraint is considered in (Benjaafar, Li and Daskin, 2010).
 - \rightarrow Acts as a capacity constraint.
- Four types of carbon emission constraints are proposed and analyzed in the single-item case in (Absi, D.-P., Kedad-Sidhoum, Penz and Rapine, 2013).
 - → Theses constraints do not limit lot sizes, but **limit the** carbon emission per unit of product.
 - \rightarrow See presentation of S. Kedad-Sidhoum.



Independent demands (for end products) and dependent demands



Multi-Level Lot Sizing

New parameter g_{ij} : Number of items *i* necessary to produce one unit of item *j* (*gozinto factor*).

New inventory balance equation becomes a coupling constraint.



Multi-Level Lot Sizing

See presentation of J.-P. Casal (FuturMaster).

Various approaches have been proposed:

- Lagrangian relaxation (Tempelmeier and Derstroff, 1996),
- MIP-based heuristics (used in general for complex lot-sizing problems).



• Iterative approaches.

- Solve at each stage a reduced mixed integer problem.
- By reducing the number of binary variables and the number of constraints.
- Various decompositions can be used::
 - An horizon-oriented decomposition,
 - A product-oriented decomposition,
 - A resource-oriented decomposition,
 - A process-oriented decomposition, etc.



MIP-based heuristics for Lot Sizing

Several variants:

- **Relax-and-Fix, Fix-and-Relax** (Kelly 2002, Clark 2003, Mercé and Fontan 2003, Stadtler 2003, Pochet and Van Vyve 2004, Absi and kedad-Sidhoum 2007, Federgruen et al. 2007, Seeanner et al. 2013),
- **Fix-and-Optimize** (Sahling et al. 2009, S Helber, F Sahling 2010, Lang and Shen 2011, James and Almada-Lobo 2011).



MIP-based heuristics for Lot Sizing

Example of an horizon-oriented decomposition (Absi and Kedad-Sidhoum 2007) – Relax-and-Fix



Approximation window



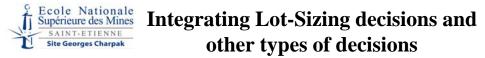
Decision window



Frozen window

Step 1

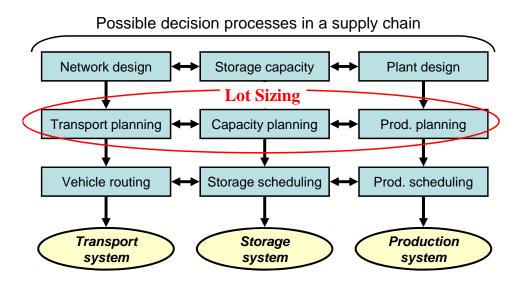
 $\delta:$ Size of decision windows $\sigma: \mbox{Overlapping section}$

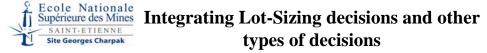


More and more researchers are studying the integration of lotsizing decisions with decisions taken at other levels or other stages in the supply chain.



Ecole Nationale Supérieure des Mines Integrating Lot-Sizing decisions and other types of decisions





Variables at different levels/stages are often of different nature, i.e. no longer pure continuous or integer optimization problems

→ Makes the integration particularly complex and changes the nature of the problems.

Objectives at different levels/stages may be of different nature, e.g. cost minimization vs. time criteria.



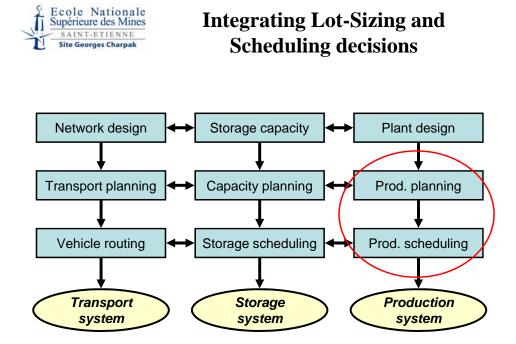
Integrating Lot-Sizing and Cutting-Stock decisions

Column Generation approaches are used in (Nonås and Thorstenson, 2000) and (Nonås and Thorstenson, 2008) to solve a combined lot-sizing and cutting-stock problem.

(Gramani and França, 2006) analyzes the trade-off in industrial problems, where trim loss, storage and setup costs are minimized. The problem is solved using a network shortest path formulation.

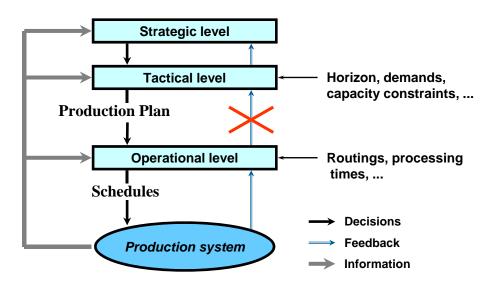
(Gramani, França and Arenales, 2009) proposes a Lagragian relaxation heuristic.

Heuristics are also proposed in (Poltroniere, Poldi, Toledo and Arenales, 2008)





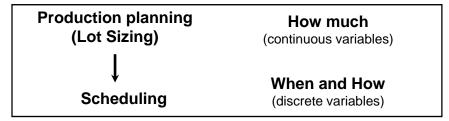
Integrating Lot-Sizing and Scheduling decisions





Integrating Lot-Sizing and Scheduling decisions

Planning and scheduling can hardly be treated simultaneously



Aggregate (necessary) capacity constraints are used

- \rightarrow No *actual* schedule to satisfy the plan
- \rightarrow Delays, work-in-process inventories



Integrating Lot-Sizing and Scheduling decisions

- Integration of production planning and detailed scheduling (Lasserre 1989, D-P. and Lasserre 1994 and 2002)
 - Multi-item lot-sizing problem,
 - Combined with job-shop scheduling problem.
- Scientific challenges:
 - Multi-item lot-sizing problem with complex capacity constraints,
 - Or job-shop scheduling problem where processing times are variables.
- Practical challenges (e.g. Renault and "25% rule" in 1996).



Integrating Lot-Sizing and Scheduling decisions – A simple example

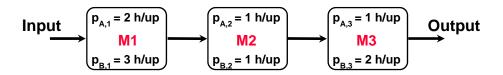
Two products A and B Three machines M1, M2 and M3

Length of a period: 60 h Quantities to be produced: XA and XB





Integrating Lot-Sizing and Scheduling decisions – A simple example

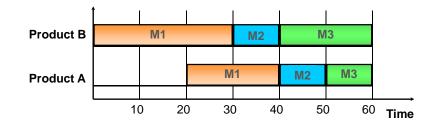


Machine constraints:

M1: 2 XA + 3 XB \leq M2: XA + XB \leq M3: XA + 2 XB \leq \rightarrow XA = 10 and XB = 10 are feasible



Integrating Lot-Sizing and Scheduling decisions – A simple example

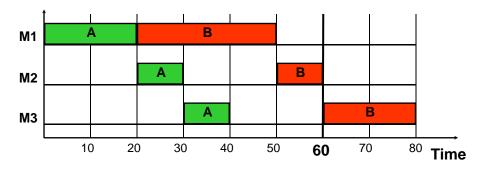


Schedule of the operations in classical planning (M.R.P.)

 \rightarrow Operations are not **sequenced**



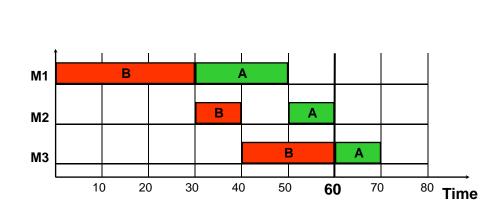
Integrating Lot-Sizing and Scheduling decisions – A simple example



Product A sequenced before product B

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Integrating Lot-Sizing and Scheduling

decisions – A simple example

Product B sequenced before product A

Cecole Nationale Supérieure des Mines SAINT-ETIENNE Site Georges Charpak	Integrating Lot-Sizing and Sched decisions	uling
$\int \min \sum_{i,l} c_i^p X_{il} + \sum_{i,l} (c_i^{in\nu} I_i^+)$	$F_l + c_l^{back} I_{il}$	(7)
$I_{il}^{+} - I_{il-1}^{-} = I_{il-1}^{+} - I_{il-1}^{-}$	$\begin{aligned} &+ c_i^{back} I_{il}^{-}) \\ &+ X_{il} - \sum_{j \in \mathscr{DP}(i)} g_{ij} X_{jl+L_j} - D_{il} \forall i, \forall l \end{aligned}$	(8)
$t_{o'} \ge t_o \cdot \mathbf{P}$ $t_{o'} \ge t_o + p_o^u X_{i(o)l(o)}$ or	lanning (Lot-Sizing) problem	(9)
or $t_o \ge t_{o'} + p_{o'}^u X_{i(o')l(o')}$	$\forall (o, o') \in \mathscr{S}(y)$	(10)
$\begin{cases} t_{o} + p_{o}^{\mu} X_{i(o)l(o)} \leq \sum_{l=1}^{l(o)} c_{l} \end{cases}$	$\forall o \in \mathscr{S}$	(11)
$t_o + p_o^u X_{i(o)l(o)} \ge \sum_{l=1}^{l(o)-1} c_l$	$\forall o \in \mathscr{S}$	(12)
$\begin{cases} or \\ t_{o} \ge t_{o'} + p_{o'}^{u} X_{i(o')l(o')} \\ t_{o} + p_{o'}^{u} X_{i(o)l(o)} \le \sum_{l=1}^{l(o)} c_{l} \\ t_{o} + p_{o'}^{u} X_{i(o)l(o)} \ge \sum_{l=1}^{l(o)-1} c_{l} \\ t_{o} \ge \sum_{l=1}^{l(o)-L_{i(o)}} c_{l} \end{cases}$	$\forall o \in \mathscr{F} \text{ such that } L_{i(o)} > 0$	(13)
$X_{il}, X_{il},$	Scheduling problem	(14) (15)
$(t_o \ge 0)$		(10)



Integrating Lot-Sizing and Scheduling decisions

• A **two-level iterative procedure** has been used to solve the problem (Lasserre 1989, D.-P. and Lasserre 1994, 2002, Roux, D.-P. and Lasserre 1999)

Comparison between **feasible** production plans obtained with aggregate model and integrated model with one-pass and iterative procedures

Problem	Total inventory an		Total inventory and ba	klog costs
Problem	Aggregate	One-pass	Iterative	
1	7538	5248	4347	
2	17036	12638	12246	
3	6318	3913	2651	
4	2457	883	133	
5	3318	482	220	
6	698	0	0	

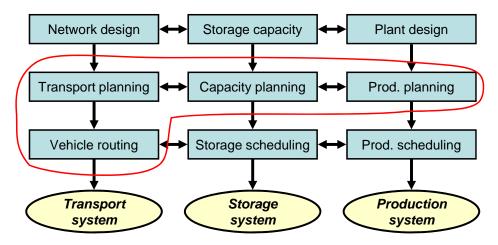


Integrating Lot-Sizing and Scheduling decisions

- A **two-level iterative procedure** has been used to solve the problem (Lasserre 1989, D.-P. and Lasserre 1994, 2002, Roux, D.-P. and Lasserre 1999)
- More recently an **integrated approach** has been proposed in (Wolosewicz, D.-P. and Aggoune, 2008)
 - → Pursued in PhD thesis of Edwin Gomez for multi-level lotsizing problems in a supply chain
- Novel formulation based on **graph representation** of scheduling problem, where *each path corresponds to a capacity constraint*.
 - \rightarrow Exponential number of capacity constraints
 - → Lagrangian relaxation approach where violated paths are inserted one by one with positive Lagrangian multiplier



• Integrated optimization of **production**, **distribution** and **inventory** decisions.



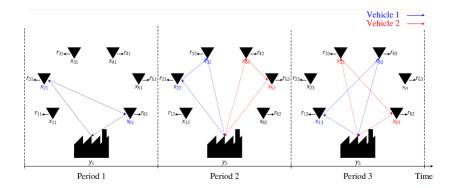


Integrating Lot Sizing and Routing *Production Routing Problem (PRP)*

- Integrated optimization of **production**, **distribution** and **inventory** decisions.
- The PRP simultaneously optimizes production, inventory and routing so that final demands of customers and inventory limits in production facility and retailers are satisfied, while minimizing all types of costs.



• Decide when and how much to produce, when, how much and how to transport in order to satisfy customer demands over a discrete time horizon





Integrating Lot Sizing and Routing *Production Routing Problem (PRP)*

Literature review

- Few papers address the PRP.
- The problem of integrating production and routing decisions was introduced by (Chandra, 1993).
- Most authors used heuristic methods to solve the problem of integrating production planning and vehicle routing (Boudia et al., 2007), (Bard et al., 2009), (Adulyasak et al. 2012), (Absi et al., 2013).
- Very few authors used exact methods (Archetti et al., 2011).
- More authors addressed the Inventory Routing Problem (IRP), which does not consider production.



Mathematical model

- Minimize production, inventory and routing costs subject to:
 - Inventory balance constraints for retailers and production facility,
 - Inventory capacity constraints for retailers and production facility,
 - Production constraints,
 - Vehicle capacity constraints,
 - Routing constraints.



Integrating Lot Sizing and Routing Production Routing Problem (PRP)

Solution approach (Absi, Archetti, Feillet and D.-P. 2012)

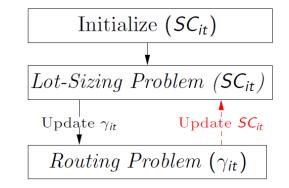
- Iterative two-phase approach.
- Routing costs incurred when visiting a customer at a given period are approximated and denoted SC_{it}.

→ Initial model can then be transformed into a lot-sizing model that optimizes production and inventory levels.

- Distribution costs only interfere with the lot-sizing model through the setup costs SC_{it} .
- First phase is called **Lot-sizing Problem** (*SC*_{*ii*}).
- Using the solution obtained in first phase, routing decisions are taken in second phase, called **Routing Problem** (γ_{vit}) .
 - \rightarrow Corresponds to solving the vehicle routing problem once the γ_{vit} variables are fixed.



Solution approach (general scheme)



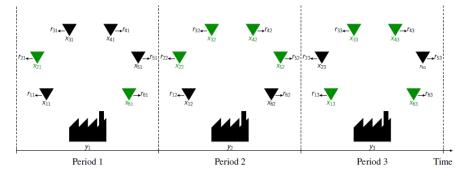
Diversification mechanism: SC_{it} multiplied by coefficient (route length) when customer *i* belongs to existing route at period *t*.



Integrating Lot Sizing and Routing *Production Routing Problem (PRP)*

Lot-sizing phase

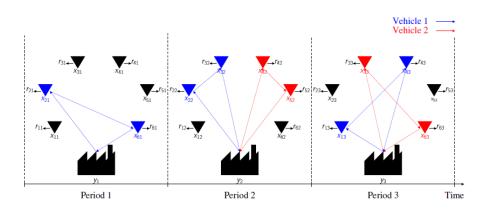
- Optimize production plan with approximated routing costs *SC_{it}* (setup costs),
- Decide when (γ_{vit}) and how much to produce, when and how much to transport in order to satisfy customer demands.





Routing phase

• Decide **how** to transport goods in order to satisfy customers and vehicles capacities (Vehicle Routing Problem).





Integrating Lot Sizing and Routing *Production Routing Problem (PRP)*

Computational experiments

- Stops after 20 iterations.
- When solution not improved for 5 iterations, diversification mechanism is used.
- Comparison with heuristics of (Archetti et al., 2011) (H) and (Adulyasak et al., 2012) (Op-ALNS).



Computational experiments

Instance set	A1	A2	A3
No. of instances	480	480	480
No. of periods	6	6	6
No. of retailers	14	50	100
No. of trucks	1	∞	∞
Demand	С	С	С
Production capacity	∞	∞	∞
Plant inventory capacity	∞	∞	∞
Retailer inventory capacity	С	С	С
Initial inventory at plant	0	0	0
Initial inventory at retailers	V	V	V
Vehicle capacity	С	С	С
V Vanving C Constant	\sim	Inlimi	tod

V - Varying, C - Constant, ∞ - Unlimited

Table: Overview of the benchmark instances (Archetti et al. 2011)



Integrating Lot Sizing and Routing *Production Routing Problem (PRP)*

Computational experiments

Class Type	Descriptions
Class 1-24	Standard instances
Class II 25-48	High production unit cost, $ imes 10$
Class III 49-72	Large transportation costs, $ imes 5$
Class IV 73-96	No retailer inventory costs

Table: Descriptions of instances classes (Archetti et al. 2011)



Computational results

Average gaps to best solutions for 480 instances of set A1.

Classes	IM	Н	ALNS
1	0,13%	2,13%	1,65%
2	0,02%	0,30%	0,36%
3	0,71%	3,43%	7,60%
4	0,07%	0,88%	0,93%
All	0,23%	1,68%	2,64%



Integrating Lot Sizing and Routing Production Routing Problem (PRP)

Computational results

Average gaps to best solutions for 480 instances of set A2.

Average gaps to best solutions for 480 instances of set A3.

Classes	IM	Н	ALNS
1	0,04%	1,89%	0,98%
2	0,02%	0,35%	0,14%
3	0,26%	2,66%	2,66%
4	0,04%	1,17%	0,13%
All	0,09%	1,52%	0,98%
	TD 6	TT	
Classes	IM	H	ALNS
1	0,06%	2,06%	0,82%
1 2	0,06% 0,19%	2,06% 0,32%	0,82% 0,29%
-	,	,	,
2	0,19%	0,32%	0,29%



Conclusions

- Lot sizing is (again...) an active field of research.
- Numerous topics were not discussed in this presentation such as: sequence-dependent setup times, joint setups, inventory bounds, stochastic lot sizing, various solution approaches (Column Generation, metaheuristics, ...), ...
- A lot of research remains to be done on the interface between lot sizing and other problems to define, in particular with industry, relevant combined problems.